

L Number	Hits	Search Text	DB	Time stamp
-	1	"20030009259"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/07 16:57
-	283	180/8.6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/06/09 14:36
-	9	("5369346"   "5402050"   "5416393"   "5594644"   "5737217"   "5823845"   "5872893"   "5982389"   "6021363"   "2002/0007230").PN.	USPAT	2003/06/09 14:43
-	1	6493606.URPN.	USPAT	2003/06/09 14:44
-	3	("6438454"   "6472839"   "6493606").PN.	USPAT	2003/06/09 14:45
-	0	6556892.URPN.	USPAT	2003/06/09 14:45
-	1785	robot and leg and sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/21 23:43
-	159	(robot and leg and sensor) and "relative movement"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/05 16:26
-	57	((robot and leg and sensor) and "relative movement") and (foot or feet)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 14:43
-	0	2001277159.URPN.	USPAT	2003/09/05 16:42
-	3	("6438454"   "6472839"   "6493606").PN.	USPAT	2003/09/05 16:42
-	0	6556892.URPN.	USPAT	2003/09/05 16:44
-	212	901/1 and (foot or feet)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/05 16:45
-	155	(901/1 and (foot or feet)) and sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/05 16:49
-	24	"6211861"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/05 16:49
-	590	robot and leg and sensor and ball	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/21 23:43
-	240	(robot and leg and sensor and ball) and image	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/21 23:43
-	175	((robot and leg and sensor and ball) and image) and controller	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/21 23:44
-	12	"5357433"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/11 11:41

-	0	"5357433" AND IMAGE	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/11 11:36
-	0	5357433.pn. AND IMAGE	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/11 11:36
-	173	robot and leg and "image processing"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/11 11:42
-	115	(robot and leg and "image processing") and relative	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/11 11:43
-	95	((robot and leg and "image processing") and relative) and sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/11 11:45
-	9	((((robot and leg and "image processing") and relative) and sensor) and "relative movement"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/11 11:55
-	94	((((robot and leg and "image processing") and relative) and sensor) and time	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/11 11:55
-	93	701/\$.ccls. and robot and imaging	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/11 16:26
-	103	701/\$.ccls. and robot and imag\$5 and foot	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/11 16:27
-	38	701/\$.ccls. and robot and imag\$5 and foot and leg	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/15 10:06
-	3	("5158493"   "5378969"   "6266578").PN.	USPAT	2003/12/11 16:30
-	0	6480761.URPN.	USPAT	2003/12/11 16:31
-	40	701/\$.ccls. and robot and (sole or bottom) and foot and leg	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/15 10:08
-	20	701/\$.ccls. and robot and sole and foot and leg	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/15 10:09
-	16	701/\$.ccls. and robot and sole and foot and leg and controller	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/15 10:10
-	10	701/\$.ccls. and robot and sole and foot and leg and controller and relative	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/15 10:14

-	5	701/\$.ccls. and robot and sole and foot and leg and controller and relative and imag\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/15 10:35
-	12	701/\$.ccls. and robot and bottom and foot and leg and controller and relative and imag\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/15 10:37
-	27	robot and sole and foot and leg and controller and relative and imag\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/15 10:49
-	51	robot and sole and foot and leg and controller and relative	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/15 11:11
-	26	(robot and sole and foot and leg and controller and relative) and normal and parallel	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/12/15 11:11
-	14	robot and foot and sole and sensor and "relative movement"	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/07 15:12
-	5	((robot and foot and sole and sensor and "relative movement") and zmp	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/07 15:12
-	11	((robot and foot and sole and sensor and "relative movement") and moment	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/07 15:12
-	8	((robot and foot and sole and sensor and "relative movement") and moment) and zero	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/07 15:12
-	8	((((robot and foot and sole and sensor and "relative movement") and moment) and zero) and point	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/07 15:13
-	3	"5944390"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/07 17:07
-	8	"5282460"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/07 17:07
-	2	"10231203"	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/08 10:58
-	24	"231203"	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/08 11:00
-	20	"239043"	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/08 11:01
-	9	"6317652"	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/08 12:14

-	6	("4703240"   "4811229"   "5378969"   "5402050"   "5416393"   "5421426").PN.	USPAT	2004/01/08 14:21
-	7	5737217.URPN.	USPAT	2004/01/08 14:36
-	8	"6317652"	USPAT	2004/01/08 14:36
-	4	("5034812"   "5402050"   "5416393"   "5986746").PN.	USPAT	2004/01/08 14:40
-	7	6317652.URPN.	USPAT	2004/01/08 14:42
-	36	((robot and leg and sensor) and "relative movement") and (foot or feet) and optic\$5	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 14:48
-	42	((robot and leg) and "relative movement") and (foot or feet) and optic\$5	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 14:48
-	274	(robot and leg) and relative and movement and (foot or feet) and optic\$5	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:36
-	82	((robot and leg) and relative and movement and (foot or feet) and optic\$5) and photo\$5	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:33
-	101	(robot and leg) and relative and movement and (foot or feet) and photo\$5	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:36
-	60	(robot and leg) and relative and movement and (foot or feet) and photo\$5	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:38
-	499	(robot and leg) and relative and movement and (foot or feet)	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:38
-	171	(robot and leg) and relative and movement and (foot or feet) and image\$5	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:39
-	180	(robot and leg) and relative and (foot or feet) and time and image\$5	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:46
-	7	robot and (leg NEAR relative) and (foot or feet) and time and image\$5	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:47
-	15	robot and (leg NEAR relative) and (foot or feet) and time	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:49
-	1907	robot and "relative movement"	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:55
-	1426	(robot and "relative movement") and time	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:50
-	1033	((robot and "relative movement") and time) and parallel	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:50
-	321	((robot and "relative movement") and time) and parallel) and calculat\$4	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:51

-	199	(((robot and "relative movement") and time) and parallel) and calculat\$4) and normal	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:52
-	0	(((robot and "relative movement") and time) and parallel) and calculat\$4) and normal) and chron\$7	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:52
-	135	(((robot and "relative movement") and time) and parallel) and calculat\$4) and normal) and seque\$7	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:53
-	19	(((robot and "relative movement") and time) and parallel) and calculat\$4) and normal) and seque\$7) and walk\$5	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:53
-	105	robot and "relative movement" and walk\$5	USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/01/08 15:56
-	158	(robot and leg) and relative and movement and (foot or feet) and sound	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/09 14:21